

# Main Theorems in SLP regarding Dynamic Programming

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## Disclaimer

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## Chapter 3 *Mathematical Preliminaries*

**Definition** Let  $(S, \rho)$  be metric space and  $T : S \rightarrow S$  be a function mapping  $S$  into itself.  $T$  is a **contraction mapping** with modulus  $\beta$  if for some  $\beta \in (0, 1)$  it holds  $\rho(Tx, Ty) < \beta\rho(x, y) \forall x, y \in S$ .

**Theorem 3.2 (Contraction Mapping Theorem)** If  $(S, \rho)$  is a complete metric space and  $T : S \rightarrow S$  is a contraction mapping with modulus  $\beta$ , then

- $T$  has exactly one fixed point  $v$  in  $S$  and
- for any  $v_0 \in S$ ,  $\rho(T^n v, v) \leq \beta^n \rho(v_0, v)$ ,  $n = 0, 1, 2, \dots$

**Corollary 1** Let  $(S, \rho)$  be a metric space, and let  $T : S \rightarrow S$  be a contraction mapping with a fixed point  $v \in S$ . If  $S'$  is a closed subset of  $S$  and  $T(S') \subseteq S'$ , then  $v \in S'$ . If in addition  $T(S') \subseteq S'' \subseteq S'$ , then  $v \in S''$ .

**Theorem 3.3 (Blackwell's sufficient conditions for a contraction)** Let  $x \subseteq \mathbf{R}^l$ , and let  $B(X)$  be a space bounded functions  $f : X \rightarrow \mathbf{R}$ , with the sup norm. Let  $T : B(X) \rightarrow B(X)$  be an operator satisfying

- (monotonicity)  $f, g \in B(X)$  and  $f(x) \leq g(x), \forall x \in X$  implies  $(Tf)(x) \leq (Tg)(x), \forall x \in X$
- (discounting) there exists some  $\beta \in (0, 1)$  such that

$$[T(f + a)](x) \leq (Tf)(x) + \beta a \quad \text{all } f \in B(X), a \geq 0, x \in X$$

Then  $T$  is a contraction with modulus  $\beta$ . (Here by definition  $(f + a)(x) = f(x) + a$ )

**Definition** A correspondence  $\Gamma : X \rightarrow Y$  is **lower hemi-continuous** (l.h.c) at  $x \in X$  if  $\Gamma(x)$  is nonempty and if, for every  $y \in \Gamma(x)$  and every sequence  $x_n \rightarrow x$ , there exists  $N \geq 1$  and a sequence  $\{y_n\}_{n=N}^{\infty}$  such that  $y_n \rightarrow y$  and  $y_n \in \Gamma(x_n)$ , all  $n \geq N$ . If  $\Gamma(\cdot)$  is nonempty-valued on  $X$ , then it is always possible to take  $N = 1$ .

$\Gamma : X \rightarrow Y$  is l.h.c. on  $X$  if  $\forall x \in X \Gamma(x) \neq \emptyset$  and  $\forall y \in \Gamma(x) \forall \{x_n\}$  such that  $x_n \rightarrow x \exists N \geq 1 \exists \{y_n\}_{n=N}^{\infty}$  such that  $y_n \in \Gamma(x_n), \forall n \geq N$  and  $y_n \rightarrow y$

**Definition** A compact-valued correspondence  $\Gamma : X \rightarrow Y$  is **upper hemi-continuous** (u.h.c) at  $x \in X$  if  $\Gamma(x)$  is nonempty and if, for every sequence  $x_n \rightarrow x$ , and every sequence  $\{y_n\}$  such that  $y_n \in \Gamma(x_n)$ , all  $n$ , there exists a convergent subsequence of  $\{y_n\}$  whose limit point is in  $\Gamma(x)$ .

$\Gamma : X \rightarrow Y$  is u.h.c. on  $X$  if  $\forall x \in X \Gamma(x) \neq \emptyset$  and  $\forall \{x_n\}$  such that  $x_n \rightarrow x \forall \{y_n\}$  such that  $\forall n y_n \in \Gamma(x_n) \exists \{y_{n_k}\}$  such that  $y_{n_k} \rightarrow y, y \in \Gamma(x)$

**Theorem 3.4** Let  $\Gamma : X \rightarrow Y$  be a nonempty-valued correspondence, and let  $A$  be the graph of  $\Gamma$ . Suppose that  $A$  is closed, and that for any bounded set  $\hat{X} \subseteq X$ , the set  $\Gamma(\hat{X})$  is bounded. Then  $\Gamma$  is compact-valued and u.h.c.

**Theorem 3.6 (Theorem of Maximum)** Let  $X \subseteq \mathbf{R}^l$  and  $Y \subseteq \mathbf{R}^m$ , let  $f : X \times Y \rightarrow \mathbf{R}$  be a continuous function, and let  $\Gamma : X \rightarrow Y$  be a compact-valued and continuous correspondence. Then the function  $h : X \rightarrow \mathbf{R}$ ,  $h(x) = \max_{y \in \Gamma(x)} f(x, y)$  is continuous, and the correspondence  $G : X \rightarrow Y$ ,  $G(x) = \{y \in \Gamma(x) : f(x, y) = h(x)\}$  is nonempty-valued, compact-valued and u.h.c.

## Chapter 4 Dynamic Programming under Certainty

Let  $X$  be a subset of an Euclidean space, and let

$$\begin{aligned} \Gamma &: X \rightarrow X \\ A &= \{(x, y) \in X \times X : y \in \Gamma(x)\} \\ F &: A \rightarrow \mathbf{R} \\ \Pi(x_0) &= \{\{x_t\}_{t=0}^{\infty} : x_{t+1} \in \Gamma(x_t), t = 0, 2, \dots\} \end{aligned}$$

Sequential problem

$$\begin{aligned} \text{(SP)} \quad & \sup_{\{x_{t+1}\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \beta^t F(x_t, x_{t+1}) \\ \text{s.t.} \quad & x_{t+1} \in \Gamma(x_t), \quad t = 0, 1, 2, \dots \\ & x_0 \in X \text{ given} \end{aligned}$$

Functional equation

$$\text{(FE)} \quad v(x) = \sup_{y \in \Gamma(x)} [F(x, y) + \beta v(y)], \quad \text{all } x \in X$$

Define  $u_n : \Pi(x_0) \rightarrow \mathbf{R}$ ,  $u : \Pi(x_0) \rightarrow \mathbf{R}$ ,  $v^* : X \rightarrow \mathbf{R}$  as

$$\begin{aligned} u_n(\tilde{x}) &= \sum_{t=1}^n \beta^t F(x_t, x_{t+1}) \\ u(\tilde{x}) &= \lim_{n \rightarrow \infty} u_n(\tilde{x}) \\ v^*(x_0) &= \sup_{\tilde{x} \in \Pi(x_0)} u(\tilde{x}) \end{aligned}$$

**Assumption 4.1**  $\Gamma(x)$  is nonempty, for all  $x \in X$

**Assumption 4.2** For all  $x_0 \in X$  and  $\tilde{x} \in \Pi(x_0)$ ,  $\lim_{n \rightarrow \infty} \sum_{t=0}^n \beta^t F(x_t, x_{t+1})$  exists in  $\bar{\mathbf{R}}$ .

**Assumption 4.3**  $X$  is a convex subset of  $\mathbf{R}^l$ , and the correspondence  $\Gamma : X \rightarrow X$  is nonempty, compact-valued and continuous.

**Assumption 4.4** The function  $F : A \rightarrow \mathbf{R}$  is bounded and continuous, and  $0 < \beta < 1$ .

**Assumption 4.5** For each  $y$ ,  $F(x, y)$  is strictly increasing in each of its first  $l$  arguments.

**Assumption 4.6**  $\Gamma$  is monotone in the sense that  $x \leq x'$  implies  $\Gamma(x) \subseteq \Gamma(x')$ .

**Assumption 4.7**  $F$  is strictly concave, that is

$$F(\theta(x, y) + (1 - \theta)(x', y')) \geq \theta F(x, y) + (1 - \theta)F(x', y'), \quad \text{all } (x, y), (x', y') \in A, \text{ and all } \theta \in (0, 1)$$

and the inequality is strict is  $x \neq x'$ .

**Assumption 4.8**  $\Gamma$  is convex in the sense that for any  $\theta \in (0, 1)$ , and any  $x, x' \in X$   $y \in \Gamma(x)$ ,  $y' \in \Gamma(x')$  implies  $\theta y + (1 - \theta)y' \in \Gamma(\theta x + (1 - \theta)x')$ .

**Assumption 4.9**  $F$  is continuously differentiable on the interior of  $A$ .

**Theorem 4.2** Let  $X, \Gamma, F$  and  $\beta$  satisfy Assumptions 4.1-4.2. Then the function  $v^*$  satisfies (FE).

**Theorem 4.3** Let  $X, \Gamma, F$  and  $\beta$  satisfy Assumptions 4.1-4.2. If  $v$  is the solution to (FE) and satisfies

$$\lim_{n \rightarrow \infty} \beta^n v(x_n) = 0, \quad \text{all } (x_0, x_1, \dots) \in \Pi(x_0), \text{ all } x_0 \in X$$

then  $v = v^*$ .

**Theorem 4.4** Let  $X, \Gamma, F$  and  $\beta$  satisfy Assumptions 4.1-4.2. Let  $\underline{x}^* \in \Pi(x_0)$  be a feasible plan that attains the supremum in (SP) for initial state  $x_0$ . Then

$$v^*(x_t^*) = F(x_t^*, x_{t+1}^*) + \beta v(x_{t+1}^*), \quad t = 0, 1, 2, \dots$$

**Theorem 4.5** Let  $X, \Gamma, F$  and  $\beta$  satisfy Assumptions 4.1-4.2. Let  $\underline{x}^* \in \Pi(x_0)$  be a feasible plan from  $x_0$  satisfying

$$v^*(x_t^*) = F(x_t^*, x_{t+1}^*) + \beta v(x_{t+1}^*), \quad t = 0, 1, 2, \dots$$

and with

$$\limsup_{t \rightarrow \infty} \beta^t v^*(x_t^*) \leq 0.$$

Then  $\underline{x}^*$  attains the supremum in (SP) for initial state  $x_0$ .

**Theorem 4.6** Let  $X, \Gamma, F$  and  $\beta$  satisfy Assumptions 4.3-4.4, and let  $C(X)$  be the space of bounded continuous functions  $f : X \rightarrow \mathbf{R}$ , with the supnorm  $\|f\| = \sup_{x \in X} |f(x)|$ . Then the operator  $T$  on  $C(X)$  defined by

$$(Tf)(x) = \max_{y \in \Gamma(x)} [F(x, y) + \beta f(y)]$$

maps  $C(X)$  into itself,  $T : C(X) \rightarrow C(X)$ ; it has a unique fixed point  $v \in C(X)$ ; and for all  $v_0 \in C(X)$ ,

$$\|T^n v_0 - v\| \leq \beta^n \|v_0 - v\|, \quad n = 0, 1, 2, \dots$$

Moreover given  $v$  the optimal policy correspondence  $G : X \rightarrow X$  defined by

$$G(x) = \{y \in \Gamma(x) : v(x) = F(x, y) + \beta v(y)\}$$

is compact-valued and u.h.c.

**Theorem 4.7** Let  $X, \Gamma, F$  and  $\beta$  satisfy Assumptions 4.3-4.6, and let  $v$  be a unique solution to

$$v(x) = \max_{y \in \Gamma(x)} F(x, y) + \beta v(y)$$

then  $v$  is strictly increasing.

**Theorem 4.8** Let  $X, \Gamma, F$  and  $\beta$  satisfy Assumptions 4.3-4.4, and 4.7-4.8, let  $v$  be a unique solution to

$$v(x) = \max_{y \in \Gamma(x)} F(x, y) + \beta v(y)$$

and  $G$  satisfy

$$G(x) = \{y \in \Gamma(x) : v(x) = F(x, y) + \beta v(y)\}$$

then  $v$  is strictly concave and  $G$  is a continuous, single-valued function.

**Theorem 4.11** Let  $X, \Gamma, F$  and  $\beta$  satisfy Assumptions 4.3-4.4, and 4.7-4.9, let  $v$  and  $g$  satisfy

$$v(x) = \max_{y \in \Gamma(x)} F(x, y) + \beta v(y)$$

and

$$g(x) = \{y \in \Gamma(x) : v(x) = F(x, y) + \beta v(y)\}$$

If  $x_0 \in \text{int}X$  and  $g(x_0) \in \Gamma(x_0)$ , then  $v$  is continuously differentiable at  $x_0$ , with derivatives given by  $v_i(x_0) = F_i(x_0, g(x_0))$ ,  $i = 1, 2, \dots, l$ .

## Constant Returns to Scale

**Assumption 4.10**  $X \subseteq \mathbf{R}^l$  is a convex cone. The correspondence  $\Gamma : X \rightarrow X$  is nonempty, compact-valued, and continuous; for any  $x \in X$ ,

$$y \in \Gamma(x) \text{ implies } \lambda y \in \Gamma(\lambda x), \text{ all } \lambda > 0$$

that is, graph of  $\Gamma$  is cone. In addition, for some  $\alpha \in (0, \beta^{-1})$ ,

$$\|y\|_l \leq \alpha \|x\|_l, \text{ all } y \in \Gamma(x), \text{ all } x \in X$$

**Assumption 4.11** The function  $F : A \rightarrow \mathbf{R}$  is continuous and homogeneous of degree one, and for some  $0 < B < \infty$

$$|F(x, y)| \leq B(\|x\|_l + \|y\|_l), \text{ all } (x, y) \in A$$

and  $\beta \in (0, 1)$ .

**Exercise 4.6** Under Assumptions 4.10-4.11  $\|x_t\|_l \leq \alpha^t \|x_0\|_l$ , for all  $x_0 \in X$ , all  $\{x_t\} \in \Pi(x_0)$ , Assumptions 4.1-4.2 hold, and the supremum function  $v^* : X \rightarrow \mathbf{R}$  is homogeneous of degree one, and for some  $0 < c < \infty$  satisfies  $|v^*(x)| \leq c \|x\|_l$ , all  $x \in X$ .

**Exercise 4.7** Let  $H(X)$  be the space of functions  $f : X \rightarrow \mathbf{R}$  that are continuous and homogeneous of degree one, and bounded in the norm

$$\|f\| = \max_{\|x\|=1, x \in X} |f(x)|$$

Then  $H(X)$  is a Banach space (a complete normed vector space) and under Assumptions 4.10-4.11 operator

$$(Tf)(x) = \sup_{y \in \Gamma(x)} [F(x, y) + \beta v(y)]$$

maps  $H(X)$  into itself, that is  $T : H(X) \rightarrow H(X)$ .

For any  $f$  homogeneous of degree 1, and any  $a \in \mathbf{R}$  define  $f + a$  by

$$(f + a)(x) = f(x) + a\|x\|$$

Since  $f$  is homogeneous of degree one and  $\|\lambda x\| = \lambda\|x\|$  for all  $\lambda > 0$ , also  $f + a$  is homogeneous of degree one.

**Theorem 4.12** *Let  $X$  be a convex cone,  $H(X)$  be a space of continuous, homogeneous of degree 1 functions, bounded in the norm  $\max_{\|x\|=1, x \in X} |f(x)|$ , and let the mapping  $T : H(X) \rightarrow H(X)$  satisfy*

- a. *monotonicity: for any  $f, g \in H(X)$ , if  $f \leq g$  then  $Tf \leq Tg$*
  - b. *discounting: exists  $\gamma \in (0, 1)$  such that for all  $f \in H$  and all  $a > 0$ ,  $T(f + a) \leq Tf + \gamma a$*
- Then  $T$  is a contraction with modulus  $\gamma$ .*

**Theorem 4.13** *Let  $X, \Gamma, F$  and  $\beta$  satisfy Assumptions 4.10 and 4.11, and let  $H(X)$  be a space of continuous, homogeneous of degree 1 functions, bounded in the norm  $\max_{\|x\|=1, x \in X} |f(x)|$ . Then operator  $T$  on  $H(X)$  defined by*

$$(Tf)(x) = \sup_{y \in \Gamma(x)} [F(x, y) + \beta v(y)]$$

*maps  $H(X)$  into itself, that is  $T : H(X) \rightarrow H(X)$ , and has a unique fixed point  $v^* \in H(x)$ . In addition*

$$\|T^n v_0 - v^*\| \leq (\alpha\beta)^n \|v_0 - v^*\|, \quad n = 0, 1, 2, \dots, \text{ all } v_0 \in H(X)$$

*and the associated policu correspondence  $G : X \rightarrow X$  is a compact valued and u.h.c. Moreover,  $G$  is homogeneous of degree one, for any  $x \in X$*

$$y \in G(x) \text{ implies } \lambda y \in G(\lambda x), \text{ all } \lambda \geq 0$$

## Chapter 7 Measure Theory and Integration

**Definition** *Let  $S$  be a set and let  $\mathcal{S}$  be a family of subsets of  $S$ .  $\mathcal{S}$  is called  $\sigma$ -algebra if*

- a.  $\emptyset, S \in \mathcal{S}$ ;
- b.  $A \in \mathcal{S}$  implies  $A^c = S \setminus A \in \mathcal{S}$ ; and
- c.  $A_n \in \mathcal{S}, n = 1, 2, \dots$ , implies  $\bigcup_{n=1}^{\infty} A_n \in \mathcal{S}$ . A pair  $(S, \mathcal{S})$  where  $S$  is a set and  $\mathcal{S}$  is a  $\sigma$ -algebra of its subsets is called a **measurable space**. Any set  $A \in \mathcal{S}$  is called an  **$\mathcal{S}$ -measurable set**.

**Definition** *The smallest  $\sigma$ -algebra containing all the open sets of the form  $(-\infty, b), (a, b), (a, +\infty), (-\infty, +\infty)$  is called a **Borel algebra** for  $\mathbf{R}^1$  and is denoted by  $\mathcal{B}^1$ , any set in  $\mathcal{B}^1$  is called a **Borel set**.*

*In general, for any metric space  $(S, \rho)$  Borel algebra is the smallest  $\sigma$ -algebra containing all the open sets of the form  $A = \{s \in S : \rho(s, s_0) < \delta\}$  where  $s_0 \in S, \delta > 0$ . For  $S = \mathbf{R}^l$  with Euclidean metric the Borel algebra is denoted  $\mathcal{B}^l$ .*

*For any borel set  $S \subset \mathbf{R}^l$  we define  $\mathcal{B}_S = \{A \in \mathcal{B}^l : A \subseteq S\}$  to be the borel subsets of  $S$ .*

**Definition** *Let  $(S, \mathcal{S})$  be a measurable space. A **measure** is an extended real-valued function  $\mu : \mathcal{S} \rightarrow \bar{\mathbf{R}}$  such that*

- a.  $\mu(\emptyset) = 0$ ;
- b.  $\mu(A) \geq 0$ , all  $A \in \mathcal{S}$ ;
- c. if  $\{A_n\}_{n=1}^{\infty}$  is a countable, disjoint sequence of subsets in  $\mathcal{S}$ , then  $\mu(\bigcup_{n=1}^{\infty} A_n) = \sum_{n=1}^{\infty} \mu(A_n)$ .

**Definition** A **measure space** is a triple  $(S, \mathcal{S}, \mu)$  where  $S$  is a set,  $\mathcal{S}$  is a  $\sigma$ -algebra of its subsets, and  $\mu$  is a measure defined on  $\mathcal{S}$ .

**Definition** If  $(S, \mathcal{S})$  is a measurable space with measure  $\mu : \mathcal{S} \rightarrow \bar{\mathbf{R}}$  and in addition  $\mu(S) = 1$ , then  $\mu$  is called a **probability measure** and  $(S, \mathcal{S}, \mu)$  is a **probability space**.

**Definition** Given a measurable space  $(S, \mathcal{S})$ , a real-valued function  $f : S \rightarrow \mathbf{R}$  is  **$\mathcal{S}$ -measurable** if  $\{s \in S : f(s) \leq a\} \in \mathcal{S}$ , for all  $a \in \mathbf{R}$ . Denote by  $M(S, \mathcal{S})$  the space of measurable, extended real-valued functions on  $S$ , and by  $M^+(S, \mathcal{S})$  the subset of nonnegative functions.

**Theorem 7.4 (Pointwise convergence preserves measurability)** Let  $(S, \mathcal{S})$  and  $(T, \mathcal{T})$  be measurable spaces, and let  $\{f_n\}$  be a sequence of  $\mathcal{S}$ -measurable functions converging pointwise to  $f$  i.e.  $\lim f_n(s) = f(s)$ , all  $s \in S$ . Then  $f$  is also  $\mathcal{S}$ -measurable.

**Definition** Let  $(S, \mathcal{S})$  and  $(T, \mathcal{T})$  be measurable spaces. Then the function  $f : S \rightarrow T$  is **measurable** if the inverse image of every measurable set is measurable, that is if  $\{s \in S : f(s) \in A\} \in \mathcal{S}$ , for all  $A \in \mathcal{T}$ .

**Definition** Let  $(S, \mathcal{S})$  and  $(T, \mathcal{T})$  be measurable spaces, and let  $\Gamma$  be a correspondence of  $S$  into  $T$ . Then the function  $h : S \rightarrow T$  is a **measurable selection from  $\Gamma$**  if  $h$  is measurable and  $h(s) \in \Gamma(s)$ , all  $s \in S$ .

**Theorem 7.6 (Measurable Selection Theorem)** Let  $S \subseteq \mathbf{R}^l$  and  $T \subseteq \mathbf{R}^m$  be Borel sets, with their Borel subsets  $\mathcal{S}, \mathcal{T}$ . Let  $\Gamma : S \rightarrow T$  be a non-empty, compact-valued and u.h.c. correspondence. Then there exists a measurable selection from  $\Gamma$ .

**Theorem 7.8 (Monotone Convergence Theorem)** If  $\{f_n\}$  is a monotone increasing sequence of functions in  $M^+(S, \mathcal{S})$  converging pointwise to  $f$  then

$$\int f d\mu = \lim_{n \rightarrow \infty} \int f_n d\mu$$

**Definition** Let  $(S, \mathcal{S}, \mu)$  be a measure space, and let  $f$  be a measurable, real-valued function on  $S$ . If  $f^+$  and  $f^-$  both have finite integrals with respect to  $\mu$  then  $f$  is **integrable**, and the integral with respect to  $\mu$  is

$$\int f d\mu = \int f^+ d\mu - \int f^- d\mu$$

If  $A \in \mathcal{S}$ , the integral of  $f$  over  $A$  with respect to  $\mu$  is

$$\int_A f d\mu = \int_A f^+ d\mu - \int_A f^- d\mu$$

**Theorem 7.10 (Lebesgue Dominated Convergence Theorem)** Let  $(S, \mathcal{S}, \mu)$  be a measure space, and let  $\{f_n\}$  be a sequence of integrable functions that converges almost everywhere to a measurable function  $f$ . If there exists an integrable function  $g$  such that  $|f_n| \leq g$ , all  $n$  then  $f$  is integrable and

$$\int f d\mu = \lim_{n \rightarrow \infty} \int f_n d\mu$$

**Definition** Let  $(X, \mathcal{X})$  and  $(Y, \mathcal{Y})$  be measurable spaces, and let  $Z$  be the Cartesian product of  $X$  and  $Y$

$$Z = X \times Y = \{z = (x, y) : x \in X, y \in Y\}$$

A set  $C = A \times B \subseteq Z$  is a **measurable rectangle** if  $A \in \mathcal{X}$  and  $B \in \mathcal{Y}$ .

## Chapter 8 Markov Processes

**Definition** Let  $(Z, \mathcal{Z})$  be a measurable space. A **transition function** is a function  $Q : Z \times \mathcal{Z} \rightarrow [0, 1]$  such that

- a. for each  $z \in Z$ ,  $Q(z, \cdot)$  is a probability measure on  $(Z, \mathcal{Z})$ ; and
- b. for each  $A \in \mathcal{Z}$ ,  $Q(\cdot, A)$  is a  $\mathcal{Z}$ -measurable function.

For any  $\mathcal{Z}$ -measurable function  $f$  define  $Tf$  by

$$(Tf)(z) = \int f(z')Q(z, dz'), \quad \text{all } z \in Z$$

For any measure  $\lambda$  on  $(Z, \mathcal{Z})$  define  $T^*\lambda$  by

$$T^*\lambda(A) = \int Q(z, A)\lambda(dz), \quad \text{all } A \in \mathcal{Z}$$

**Theorem 8.1** Operator  $T$  maps the space of non-negative  $\mathcal{Z}$ -measurable, extended-real valued functions into itself, that is  $T : M^+(Z, \mathcal{Z}) \rightarrow M^+(Z, \mathcal{Z})$ . Consequently,  $T$  maps the space of bounded  $\mathcal{Z}$ -measurable functions into itself  $T : B(Z, \mathcal{Z}) \rightarrow B(Z, \mathcal{Z})$ .

**Theorem 8.2** Operator  $T^*$  maps the space of probability measures on  $(Z, \mathcal{Z})$  into itself, that is  $T^* : \Lambda(Z, \mathcal{Z}) \rightarrow \Lambda(Z, \mathcal{Z})$ .

**Definition** A transition function  $Q$  on  $(Z, \mathcal{Z})$  has the **Feller property** if the associated operator  $T$  maps the space of bounded continuous functions on  $Z$  into itself; that is, if  $T : C(Z) \rightarrow C(Z)$ .

**Definition** A transition function  $Q$  on  $(Z, \mathcal{Z})$  is **monotone** if the associated operator  $T$  has the property that for every nondecreasing function  $f : Z \rightarrow \mathbf{R}$ , the function  $Tf$  is also nondecreasing.

Let  $(Z, \mathcal{Z})$  be a measurable space and for any finite  $t = 1, 2, \dots$  let

$$(Z \times \dots \times Z, \mathcal{Z} \times \dots \times \mathcal{Z}), \quad (t\text{-times})$$

denote the product space. For any rectangle  $B = A_1 \times \dots \times A_t \in \mathcal{Z}^t$  let

$$\mu^t(z_0, B) = \int_{A_1} \dots \int_{A_t} Q(z_{t-1}, dz_t)Q(z_{t-2}, dz_{t-1}) \dots Q(z_0, dz_1)$$

## Chapter 9 Stochastic Dynamic Programming

The stochastic dynamic problems analyzed in this chapter have one of the following two forms

$$v(x, z) = \sup_{y \in \Gamma(x, z)} \left\{ F(x, y, z) + \beta \int_Z v(y, z')Q(z, dz') \right\}$$

$$v(x, z) = \sup_{y \in \Gamma(x, z)} \left\{ F(x, y, z) + \beta \int_Z v(\phi(x, y, z'), z')Q(z, dz') \right\}$$

**Type 1 problems.**

Functional equation has the form

$$v(x, z) = \sup_{y \in \Gamma(x, z)} \left\{ F(x, y, z) + \beta \int_Z v(y, z') Q(z, dz') \right\}$$

Let  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$  be measurable spaces, and let  $(S, \mathcal{S}) = (X \times Z, \mathcal{X} \times \mathcal{Z})$  and  $(Z^t, \mathcal{Z}^t)$  be product spaces. Let  $Q$  be a stationary transition function on  $(Z, \mathcal{Z})$ . Let

$$\begin{aligned} \Gamma &: X \times Z \rightarrow X \\ A &= \{(x, y, z) \in X \times X \times Z : y \in \Gamma(x, z)\} \\ F &: A \rightarrow \mathbf{R} \end{aligned}$$

be the correspondence that defines the restriction on possible actions, its graph and the one period returns function. Define further

$$\mathcal{A} = \{C \in \mathcal{X} \times \mathcal{X} \times \mathcal{Z} : C \subseteq A\}$$

Given for type 1 problem are  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F, \beta$ .

**Definition** A *plan*  $\pi = (\pi_0, \pi_1, \dots)$  is a value  $\pi_0 \in X$  and a sequence of measurable functions  $\pi_t : Z^t \rightarrow X$ ,  $t = 1, 2, \dots$

A plan  $\pi$  is **feasible from**  $s_0 \in S$  if  $\pi_0 \in \Gamma(s_0)$  and  $\pi_t(z^t) \in \Gamma(\pi_{t-1}(z^{t-1}), z_t)$ , all  $z^t \in Z^t$ ,  $t = 1, 2, \dots$ . Denote  $\Pi_0(s_0)$  the set of plans that are feasible from  $s_0$ .

**Assumption 9.1**  $\Gamma$  is nonempty-valued and the graph of  $\Gamma$  is  $(\mathcal{X} \times \mathcal{X} \times \mathcal{Z})$ -measurable. In addition,  $\Gamma$  has a measurable selection, that is there exists a measurable function  $h : S \rightarrow X$  such that  $h(s) \in \Gamma(s)$ , all  $s \in S$ .

**Assumption 9.2**  $F : A \rightarrow \mathbf{R}$  is  $\mathcal{A}$ -measurable and either (a) or (b) holds

- a.  $F \geq 0$  or  $F \leq 0$
- b. For each  $(x_0, z_0) = s_0 \in S$  and each plan  $\pi \in \Pi(s_0)$

$$F(\pi_{t-1}(z^{t-1}), \pi_t(z^t), z_t) \text{ is } \mu^t(z_0, \cdot)\text{-integrable, } t = 1, 2, \dots$$

and the limit

$$F(x_0, \pi_0, z_0) + \lim_{n \rightarrow \infty} \sum_{t=1}^n \int_{Z^t} \beta^t F(\pi_{t-1}(z^{t-1}), \pi_t(z^t), z^t) \mu^t(z_0, dz^t)$$

exists (although it may be plus or minus infinity)

**Assumption 9.3** If  $F$  takes on both signs, there is a collection of nonnegative, measurable functions  $L_t : S \rightarrow \mathbf{R}_+$ ,  $t = 0, 1, \dots$ , such that for all  $\pi \in \Pi(s_0)$  and all  $s_0 \in S$

$$\begin{aligned} |F(x_0, \pi_0, z_0)| &\leq L_0(s_0) \\ |F(\pi_{t-1}(z^{t-1}), \pi_t(z^t), z_t)| &\leq L_t(s_0), \quad \text{all } z^t \in Z^t, t = 1, 2, \dots \end{aligned}$$

and

$$\sum_{t=0}^{\infty} \beta^t L_t(s_0) < \infty$$

**Assumption 9.4**  $X$  is a convex Borel set in  $\mathbf{R}^l$ , with its Borel subsets  $\mathcal{X}$ .



**Assumption 9.5** *One of the following conditions holds:*

- a.  $Z$  is a countable set and  $\mathcal{Z}$  is the  $\sigma$ -algebra containing all subsets of  $Z$
- b.  $Z$  is a compact Borel subset in  $\mathbf{R}^k$ , with its Borel subsets  $\mathcal{Z}$ , and the transition function  $Q$  on  $(Z, \mathcal{Z})$  has the Feller property.

*Note.* We need that the operator  $T$  associated with  $Q$  maps the space of bounded continuous functions into itself. If  $Z$  is a countable set, we use discrete metric and all functions on  $Z$  are continuous, this requirement is vacuous. Notice that a sequence  $\{s_n = (x_n, z_n)\}$  in  $S$  converges to  $s = (x, z) \in S$  if and only if  $x_n \rightarrow x$  and  $z_n \rightarrow z$ . If  $Z$  is countable set a function on  $S$  is continuous if and only if each  $z$ -section  $f(\cdot, z) : X \rightarrow \mathbf{R}$  is continuous. We take  $C(S)$  the space of bounded continuous functions  $f : S \rightarrow \mathbf{R}$  with the sup norm  $\|f\| = \sup_{s \in S} |f(s)|$

**Assumption 9.6** *The correspondence  $\Gamma : X \times Z \rightarrow X$  is nonempty, compact-valued, and continuous.*

*Note.* If  $Z$  is countable Assumption 9.6 means that for each fixed  $z$  the correspondence  $\Gamma(\cdot, z) : X \rightarrow X$  is nonempty, compact valued, and continuous. Similarly, Assumption 9.7 means that for each fixed  $z$  the function  $F(\cdot, \cdot, z) : A_z \rightarrow \mathbf{R}$  is bounded and continuous.

**Assumption 9.7** *The function  $F : A \rightarrow \mathbf{R}$  is bounded and continuous, and  $\beta \in (0, 1)$ .*

**Assumption 9.8** *For each  $(y, z) \in X \times Z$ ,  $F(\cdot, y, z) : A_{yz} \rightarrow \mathbf{R}$  is strictly increasing.*

**Assumption 9.9** *For each  $z \in Z$ ,  $\Gamma(\cdot, z) : X \rightarrow X$  is increasing in the sense that  $x \leq x'$  implies  $\Gamma(x, z) \subseteq \Gamma(x', z)$ .*

**Assumption 9.10** *For each  $z \in Z$ ,  $F(\cdot, \cdot, z) : A_z \rightarrow \mathbf{R}$  is satisfies*

$$F(\theta(x, y) + (1-\theta)(x', y'), z) \geq \theta F(x, y, z) + (1-\theta)F(x', y', z), \text{ all } (x, y), (x', y') \in A_z, \text{ and all } \theta \in (0, 1)$$

*and the inequality is strict is  $x \neq x'$ .*

**Assumption 9.11** *For all  $z \in Z$ , all  $x, x' \in X$ , and for any  $\theta \in (0, 1)$ ,  $y \in \Gamma(x, z)$ ,  $y' \in \Gamma(x', z)$  implies  $\theta y + (1-\theta)y' \in \Gamma(\theta x + (1-\theta)x', z)$ .*

**Lemma 9.1** *Let  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$ ,  $\Gamma$  be given. Under Assumption 9.1,  $\Pi(s_0)$  is nonempty for all  $s_0 \in S$ .*

Under Assumption 9.1  $\mathcal{A}$  is a  $\sigma$ -algebra. If  $F$  is  $\mathcal{A}$ -measurable for any  $s_0 \in S$  and any  $\pi \in \Pi(s_0)$

$$F(\pi_{t-1}(z^{t-1}), \pi_t(z^t), z^t)$$

is  $\mathcal{Z}^t$ -measurable, for  $t = 1, 2, \dots$

Under Assumption 9.2, for any  $s_0 \in S$  we can define  $u_n(\cdot, s_0) : \Pi(s_0) \rightarrow \mathbf{R}$ ,  $n = 0, 1, \dots$  and  $u(\cdot, s_0) : \Pi(s_0) \rightarrow \overline{\mathbf{R}}$  by

$$\begin{aligned} u_0(\pi, s_0) &= F(x_0, \pi_0, z_0) \\ u_n(\pi, s_0) &= F(x_0, \pi_0, z_0) + \sum_{t=1}^n \int_{Z^t} \beta^t F(\pi_{t-1}(z^{t-1}), \pi_t(z^t), z_t) \mu^t(z_0, dz^t) \\ u(\pi, s_0) &= \lim_{n \rightarrow \infty} u_n(\pi, s_0) \end{aligned}$$

Under Assumption 9.1 and 9.2, the function  $u(\cdot, s)$  is well defined on the nonempty set  $\Pi(s)$ , for each  $s \in S$ . We can define supremum function  $v^* : S \rightarrow \overline{\mathbf{R}}$  by

$$v^*(s) = \sup_{\pi \in \Pi(s)} u(\pi, s)$$

that is it satisfies

$$\begin{aligned} v^*(s) &\geq u(\pi, s), \quad \text{all } \pi \in \Pi(s) \\ v^*(s) &= \lim_{k \rightarrow \infty} u(\pi^k, s_0), \quad \text{for some sequence } \{\pi^k\}_{k=1}^{\infty} \in \Pi(s) \end{aligned}$$

Consider now

$$\begin{aligned} v(s) = v(x, z) &= \sup_{y \in \Gamma(x, z)} \left[ F(x, y, z) + \beta \int v(y, z') Q(z, dz') \right] \quad (\text{FE}) \\ G(s) = G(x, z) &= \left\{ y \in \Gamma(x, z) : v(x, z) = F(x, y, z) + \beta \int v(y, z') Q(z, dz') \right\} \end{aligned}$$

**Theorem 9.2** Let  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F$  and  $\beta$  be given. Let Assumptions 9.1, 9.2 hold, and let  $v^*$  be the supremum function defined as above. Let  $v$  be a measurable function satisfying the functional equation (FE), and such that

$$\lim_{t \rightarrow \infty} \int_{Z^t} \beta^t v(\pi_{t-1}(z^{t-1}), z_t) \mu^t(z_0, dz^t) = 0, \quad \text{all } \pi \in \Pi(s_0), \text{ all } (x_0, z_0) = s_0 \in S$$

Let  $G$  be the correspondence defined as above, and suppose that  $G$  is nonempty and permits a measurable selection. Then  $v = v^*$ , and any plan  $\pi^*$  generated by  $G$  attains the supremum  $v^*$ .

**Theorem 9.4** Let  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F$  and  $\beta$  be given. Let Assumptions 9.1-9.3 hold, and let  $v^*$  be the supremum function defined as above. Assume that  $v^*$  is measurable and satisfies (FE), and define the correspondence  $G$  as above. Assume that  $G$  is nonempty and permits a measurable selection. Let  $(x_0, z_0) = s_0 \in S$ , and let  $\pi^* \in \Pi(s_0)$  be a plan that attains the supremum  $v^*$  for initial  $s_0$ . Then there exists a plan  $\pi^G$  generated by  $G$  from  $s_0$  such that

$$\begin{aligned} \pi_0^G &= \pi_0^* \\ \pi_t^G(z^t) &= \pi_t^*(z^t), \quad \mu^t(z_0, \cdot) \text{ almost everywhere, } t = 1, 2, \dots \end{aligned}$$

**Lemma 9.5** Let  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$  and  $Q$  satisfy Assumptions 9.4 and 9.5. If  $f : X \times Z \rightarrow \mathbf{R}$  is bounded and continuous, then  $Mf$  defined by

$$(Mf)(y, z) = \int f(y, z') Q(z, dz'), \quad \text{all } (y, z) \in X \times Z$$

is also, that is  $M : C(S) \rightarrow C(S)$ . If  $f$  is increasing (strictly increasing) in each of its first  $l$  arguments, then so is  $Mf$ ; and if  $f$  is concave (strictly concave) jointly in its first  $l$  arguments, then so is  $Mf$ .

**Exercise 9.7** If  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F$  and  $\beta$  satisfy Assumptions 9.4-9.7, then Assumptions 9.1-9.3 are satisfied.

**Theorem 9.6** Let  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F$  and  $\beta$  satisfy Assumptions 9.4-9.7, and define operator  $T$  on  $C(S)$  by

$$(Tf)(x, z) = \max_{y \in \Gamma(x, z)} \left\{ F(x, y, z) + \beta \int f(y, z') Q(z, dz') \right\}.$$

Then  $T : C(S) \rightarrow C(S)$ ;  $T$  has a unique fixed point  $v$  in  $C(S)$  and for any  $v_0 \in C(S)$

$$\|T^n v_0 - v\| \leq \beta^n \|v_0 - v\|, \quad n = 1, 2, \dots$$

Moreover, the correspondence  $G : S \rightarrow X$  defined by

$$G(x, z) = \left\{ y \in \Gamma(x, z) : v(x, z) = F(x, y, z) + \beta \int f(y, z') Q(z, dz') \right\}$$

is nonempty, compact-valued and u.h.c.

**Theorem 9.7** Let  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F$  and  $\beta$  satisfy Assumptions 9.4-9.9, and let  $v$  be a unique fixed point of the operator defined in Theorem 9.6. Then for each  $z \in Z$ ,  $v(\cdot, z) : X \rightarrow \mathbf{R}$  is strictly increasing.

**Theorem 9.8** Let  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F$  and  $\beta$  satisfy Assumptions 9.4-9.7 and 9.10-9.11; let  $v$  be a unique fixed point of the operator defined in Theorem 9.6. Then for each  $z \in Z$ ,  $v(\cdot, z) : X \rightarrow \mathbf{R}$  is strictly concave and  $G(\cdot, z) : X \rightarrow X$  is a continuous (single-valued) function.

## Type 2 problems.

Functional equation has the form

$$v(x, z) = \sup_{y \in \Gamma(x, z)} \left\{ F(x, y, z) + \beta \int_Z v(\phi(x, y, z'), z') Q(z, dz') \right\}$$

Let  $(X, \mathcal{X})$ ,  $(Z, \mathcal{Z})$ ,  $(Y, \mathcal{Y})$  be measurable spaces, and let  $(S, \mathcal{S}) = (X \times Z, \mathcal{X} \times \mathcal{Z})$  and  $(Z^t, \mathcal{Z}^t)$  be product spaces. Let  $Q$  be a stationary transition function on  $(Z, \mathcal{Z})$ . Let

$$\begin{aligned} \Gamma &: X \times Z \rightarrow Y \\ A &= \{(x, y, z) \in X \times Y \times Z : y \in \Gamma(x, z)\} \\ F &: A \rightarrow \mathbf{R} \end{aligned}$$

be the correspondence that defines the restriction on possible actions, its graph and the one period returns function. Let

$$D = \{(x, y) \in X \times Y : y \in \Gamma(x, z), \text{ for some } z \in Z\}$$

and let  $\phi : D \times Z \rightarrow X$  be the law of motion for the state variable. Define further

$$\mathcal{A} = \{C \in \mathcal{X} \times \mathcal{Y} \times \mathcal{Z} : C \subseteq A\}$$

Given for type 2 problem are  $(X, \mathcal{X})$ ,  $(Y, \mathcal{Y})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F, \beta, \phi$ .

**Definition** A **plan** is a sequence of functions  $\pi = \{\pi_t\}_{t=0}^\infty$  where  $\pi_t : Z^t \rightarrow Y$ ,  $t = 1, 2, \dots$  is  $\mathcal{Z}$ -measurable,  $t = 1, 2, \dots$

A plan  $\pi$  is **feasible from**  $s_0 \in S$  if  $\pi_0 \in \Gamma(s_0)$  and  $\pi_t(z^t) \in \Gamma(x_t^\pi(z^t), z_t)$ , all  $z^t \in Z^t$ ,  $t = 1, 2, \dots$  where the functions  $x_t^\pi : Z^t \rightarrow X$ ,  $t = 1, 2, \dots$  are defined recursively by  $x_1^\pi(z^1) = \phi(x_0, z_0, z_1)$ , all  $z_1 \in Z$  and  $x_t^\pi(z^t) = \phi(x_{t-1}^\pi(z^{t-1}), \pi_{t-1}(z^{t-1}), z_t)$ , all  $z^t \in Z^t$ ,  $t = 2, 3, \dots$ . Denote  $\Pi_0(s_0)$  the set of plans that are feasible from  $s_0$ .

**Assumption 9.1'**  $\Gamma$  is nonempty-valued and the graph of  $\Gamma$  is  $(\mathcal{X} \times \mathcal{Y} \times \mathcal{Z})$ -measurable. In addition,  $\Gamma$  has a measurable selection, that is there exists a measurable function  $h : S \rightarrow Y$  such that  $h(s) \in \Gamma(s)$ , all  $s \in S$ . In addition, the function  $\phi : D \times Z \rightarrow X$  is measurable.

**Assumption 9.2'**  $F : A \rightarrow \mathbf{R}$  is  $\mathcal{A}$ -measurable and either (a) or (b) holds

- a.  $F \geq 0$  or  $F \leq 0$
- b. For each  $(x_0, z_0) = s_0 \in S$  and each plan  $\pi \in \Pi(s_0)$

$$F(x_t^\pi(z^t), \pi_t(z^t), z^t) \text{ is } \mu^t(z_0, \cdot)\text{-integrable, } t = 1, 2, \dots$$

and the limit

$$F(x_0, \pi_0, z_0) + \lim_{n \rightarrow \infty} \sum_{t=1}^n \int_{Z^t} \beta^t F(x_t^\pi(z^t), \pi_t(z^t), z_t) \mu^t(z_0, dz^t)$$

exists (although it may be plus or minus infinity)

**Assumption 9.3'** If  $F$  takes on both signs, there is a collection of nonnegative, measurable functions  $L_t : S \rightarrow \mathbf{R}_+$ ,  $t = 0, 1, \dots$ , such that for all  $\pi \in \Pi(s_0)$  and all  $s_0 \in S$

$$\begin{aligned} |F(x_0, \pi_0, z_0)| &\leq L_0(s_0) \\ |F(x_t^\pi(z^t), \pi_t(z^t), z_t)| &\leq L_t(s_0), \quad \text{all } z^t \in Z^t, t = 1, 2, \dots \end{aligned}$$

and

$$\sum_{t=0}^{\infty} \beta^t L_t(s_0) < \infty$$

**Assumption 9.16**  $Y$  is a convex Borel set in  $\mathbf{R}^m$ , with its Borel subsets  $\mathcal{Y}$ .

**Assumption 9.17**  $\phi : D \times Z \rightarrow X$  is continuous.

**Lemma 9.1'** Let  $(X, \mathcal{X})$ ,  $(Y, \mathcal{Y})$ ,  $(Z, \mathcal{Z})$ ,  $\Gamma$ ,  $\phi$  be given. Under Assumption 9.1',  $\Pi(s_0)$  is nonempty for all  $s_0 \in S$ .

Under Assumption 9.1'  $\mathcal{A}$  is a  $\sigma$ -algebra. If  $F$  is  $\mathcal{A}$ -measurable for any  $s_0 \in S$  and any  $\pi \in \Pi(s_0)$

$$F(\pi_{t-1}(z^{t-1}), \pi_t(z^t), z^t)$$

is  $\mathcal{Z}^t$ -measurable, for  $t = 1, 2, \dots$

Under Assumption 9.2', for any  $s_0 \in S$  we can define  $u_n(\cdot, s_0) : \Pi(s_0) \rightarrow \mathbf{R}$ ,  $n = 0, 1, \dots$  and  $u(\cdot, s_0) : \Pi(s_0) \rightarrow \overline{\mathbf{R}}$  by

$$\begin{aligned} u_0(\pi, s_0) &= F(x_0, \pi_0, z_0) \\ u_n(\pi, s_0) &= F(x_0, \pi_0, z_0) + \sum_{t=1}^n \int_{Z^t} \beta^t F(x_t^\pi(z^t), \pi_t(z^t), z_t) \mu^t(z_0, dz^t) \\ u(\pi, s_0) &= \lim_{n \rightarrow \infty} u_n(\pi, s_0) \end{aligned}$$

Under Assumption 9.1' and 9.2', the function  $u(\cdot, s)$  is well defined on the nonempty set  $\Pi(s)$ , for each  $s \in S$ . We can define supremum function  $v^* : S \rightarrow \overline{\mathbf{R}}$  by

$$v^*(s) = \sup_{\pi \in \Pi(s)} u(\pi, s)$$

that is it satisfies

$$\begin{aligned} v^*(s) &\geq u(\pi, s), \quad \text{all } \pi \in \Pi(s) \\ v^*(s) &= \lim_{k \rightarrow \infty} u(\pi^k, s_0), \text{ for some sequence } \{\pi^k\}_{k=1}^{\infty} \in \Pi(s) \end{aligned}$$

Consider now

$$v(s) = v(x, z) = \sup_{y \in \Gamma(x, z)} \left[ F(x, y, z) + \beta \int v(\phi(x, y, z'), z') Q(z, dz') \right] \quad (\text{FE})$$

$$G(s) = G(x, z) = \left\{ y \in \Gamma(x, z) : v(x, z) = F(x, y, z) + \beta \int v(\phi(x, y, z'), z') Q(z, dz') \right\}$$

**Theorem 9.2'** Let  $(X, \mathcal{X})$ ,  $(Y, \mathcal{Y})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F, \beta$  and  $\phi$  be given. Let Assumptions 9.1', 9.2' hold, and let  $v^*$  be the supremum function defined as above. Let  $v$  be a measurable function satisfying the functional equation (FE), and such that

$$\lim_{t \rightarrow \infty} \int_{Z^t} \beta^t v(x_t^\pi(z^t), z_t) \mu^t(z_0, dz^t) = 0, \quad \text{all } \pi \in \Pi(s_0), \text{ all } (x_0, z_0) = s_0 \in S$$

Let  $G$  be the correspondence defined as above, and suppose that  $G$  is nonempty and permits a measurable selection. Then  $v = v^*$ , and any plan  $\pi^*$  generated by  $G$  attains the supremum  $v^*$ .

**Theorem 9.4'** Let  $(X, \mathcal{X})$ ,  $(Y, \mathcal{Y})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F, \beta$  and  $\phi$  be given. Let Assumptions 9.1'-9.3' hold, and let  $v^*$  be the supremum function defined as above. Assume that  $v^*$  is measurable and satisfies (FE), and define the correspondence  $G$  as above. Assume that  $G$  is nonempty and permits a measurable selection. Let  $(x_0, z_0) = s_0 \in S$ , and let  $\pi^* \in \Pi(s_0)$  be a plan that attains the supremum  $v^*$  for initial  $s_0$ . Then there exists a plan  $\pi^G$  generated by  $G$  from  $s_0$  such that

$$\begin{aligned} \pi_0^G &= \pi_0^* \\ \pi_t^G(z^t) &= \pi_t^*(z^t), \quad \mu^t(z_0, \cdot) \text{ almost everywhere, } t = 1, 2, \dots \end{aligned}$$

**Lemma 9.5'** Let  $(X, \mathcal{X})$ ,  $(Y, \mathcal{Y})$ ,  $(Z, \mathcal{Z})$  and  $Q$  satisfy Assumptions 9.4-9.5 and 9.16-9.17. If  $f : X \times Z \rightarrow \mathbf{R}$  is continuous, then function  $h : D \times Z \rightarrow \mathbf{R}$  defined by

$$h(z, y, z) = \int f(\phi(x, y, z'), z') Q(z, dz')$$

is also continuous.

**Exercise 9.5** If  $(X, \mathcal{X})$ ,  $(Y, \mathcal{Y})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F, \beta$  and  $\phi$  satisfy Assumptions 9.4-9.7 and 9.16-9.17, then Assumptions 9.1'-9.3' are satisfied.

**Theorem 9.6'** Let  $(X, \mathcal{X})$ ,  $(Y, \mathcal{Y})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F, \beta$  and  $\phi$  satisfy Assumptions 9.4-9.7 and 9.16-9.17, and define operator  $T$  on  $C(S)$  by

$$(Tf)(x, z) = \max_{y \in \Gamma(x, z)} \left\{ F(x, y, z) + \beta \int f(\phi(x, y, z') z') Q(z, dz') \right\}.$$

Then  $T : C(S) \rightarrow C(S)$ ;  $T$  has a unique fixed point  $v$  in  $C(S)$  and for any  $v_0 \in C(S)$

$$\|T^n v_0 - v\| \leq \beta^n \|v_0 - v\|, \quad n = 1, 2, \dots$$

Moreover, the correspondence  $G : S \rightarrow X$  defined by

$$G(x, z) = \left\{ y \in \Gamma(x, z) : v(x, z) = F(x, y, z) + \beta \int f(\phi(x, y, z') z') Q(z, dz') \right\}$$

is nonempty, compact-valued and u.h.c.

**Theorem 9.7'** Let  $(X, \mathcal{X})$ ,  $(Y, \mathcal{Y})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F, \beta$  and  $\phi$  satisfy Assumptions 9.4-9.9 and 9.16-9.17; let  $\phi$  be nondecreasing in each of the first  $l$  arguments, and let  $v$  be a unique fixed point of the operator defined in Theorem 9.6'. Then for each  $z \in Z$ ,  $v(\cdot, z) : X \rightarrow \mathbf{R}$  is strictly increasing.

**Theorem 9.8'** Let  $(X, \mathcal{X})$ ,  $(Y, \mathcal{Y})$ ,  $(Z, \mathcal{Z})$ ,  $Q, \Gamma, F, \beta$  and  $\phi$  satisfy Assumptions 9.4-9.7, 9.10-9.11, 9.16-9.17; let  $\phi(\cdot, \cdot, z')$  be concave function for each  $z' \in Z$ , and let  $v$  be a unique fixed point of the operator defined in Theorem 9.6'. Then for each  $z \in Z$ ,  $v(\cdot, z) : X \rightarrow \mathbf{R}$  is strictly concave and  $G(\cdot, z) : X \rightarrow X$  is a continuous (single-valued) function.

## References

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